

General Description

The GOTOP GGM-4538-GKBD is a complete GPS&Beidou engine module that features super sensitivity, ultra low power and small form factor. The GPS&Beidou signal is applied to the antenna input of module, and a complete serial data message with position, velocity and time information is presented at the serial interface with NMEA protocol or custom protocol.

Its -165dBm tracking sensitivity extends positioning coverage into place like urban canyons and dense foliage environment where the GPS&Beidou was not possible before. The small form factor and low power consumption make the module easy to integrate into portable device like PNDs, mobile phones, cameras and vehicle navigation systems.

Applications

- LBS (Location Based Service)
- PND (Portable Navigation Device)
- Vehicle navigation system
- Mobile phone



**Figure : GGM-4538-GKBD
Top View**

Features

- Build on high performance, low-power GK9501 chipset
- Ultra high Track sensitivity: -165dBm
- Extremely fast TTFF at low signal level
- Built in high gain LNA
- The built-in super capacitor for backup ephemeris
- Low power consumption: Max $45\text{mA}@3.3\text{V}$
- NMEA-0183 compliant protocol or custom protocol
- Operating voltage: 3.0V to 5.0V
- Operating temperature range: -40 to 85°C
- Patch Antenna Size: $25 \times 25 \times 4\text{mm}$
- Small form factor: $45 \times 38 \times 13\text{mm}$
- Communication type: UART/TTL
- Wire interface type: Molex 4Pin , L=150cm
- RoHS compliant (Lead-free)

1 Description

1.1. Key Features

Parameter	Specification
Power Supply	<ul style="list-style-type: none"> Supply voltage: 3.0V~5.0V Typical: 3.3V
Power Consumption	<ul style="list-style-type: none"> Acquisition: 45mA @VCC=VBAT=3.3V Tracking: 40mA @VCC=VBAT=3.3V Backup: 15uA @VBAT=3.3V
Receiver Type	<ul style="list-style-type: none"> Code 66 search channels, 22 synchronous tracking channels GPS&QZSS L1 1575.42MHz C/A , Beidou B1 1561.098MHz SBAS: WAAS, EGNOS, MSAS, GAGAN
Sensitivity	<ul style="list-style-type: none"> Tracking: -165dBm Re-acquisition: -156dBm Acquisition: -146dBm
TTF (Autonomous)	<ul style="list-style-type: none"> Cold start: 35s typ @-130dBm Warm start: 30s typ @-130dBm Hot start: 1s typ @-130dBm
Horizontal Position Accuracy (Autonomous)	<ul style="list-style-type: none"> <2.5m CEP @-130 dBm
Max Update Rate	<ul style="list-style-type: none"> Up to 10Hz,1Hz by fault
Accuracy of 1PPS Signal	<ul style="list-style-type: none"> not enabled
Acceleration Accuracy	<ul style="list-style-type: none"> Without aid: 0.1m/s²
Dynamic Performance	<ul style="list-style-type: none"> Maximum altitude: 18,000m Maximum velocity: 515m/s Acceleration: 4G
UART Port	<ul style="list-style-type: none"> UART Port: TXD and RXD Supports baud rate from 4800bps to 115200bps, 9600bps by default UART port is used for NMEA output, GK proprietary commands input and firmware upgrade
Temperature Range	<ul style="list-style-type: none"> Normal operation: -40°C ~ +85°C Storage temperature: -45°C ~ +125°C
Physical Characteristics	<ul style="list-style-type: none"> Size: 45±0.20 × 38±0.20 × 13±0.50mm Connecting line specifications: molex 4pin, L=150cm Weight: Approx.20g

1.2 Power Supply

Regulated power for the GGM-4538-GKBD is required. The VCC Pin Need a stable DC voltage supply. Power supply ripple must be less than 30mV. The input voltage Vcc should be 3.0V~5.0V, Recommended power supply voltage is 3.3V . maximum current is 45mA. Suitable decoupling must be provided by external decoupling circuitry.

1.3 UART Ports

The module supports two full duplex serial channels UART. All serial connections are at 3V CMOS logic levels, if need different voltage levels, use appropriate level shifters. The baud rate of both serial ports are fully programmable, the data format is however fixed: X, N, 8, 1, i.e. X baud rate, no parity, eight data bits and one stop bit, no other data formats are supported, LSB is sent first. The modules default baud rate is set up 9600bps, UART port can be used for NMEA output.

2 Application

The Gmouse is equipped with a 4-pin molex head connects to your application platform.

The GGM-4538-GKBD Gmouse It consists of a GK9501single chip GNSS IC which includes the RF part and Baseband part, a patch antenna, a LNA, a SAW filter, a TCXO, a crystal oscillator, Also comes with a 0.22F crystal capacitor ,can backup satellite ephemeris about 2 hour.

2.1. Pin Assignment

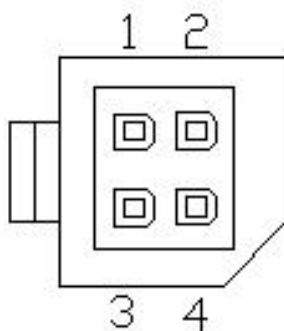


Figure 2: Pin Assignment

CON Pin Description

Pin No.	Pin name	I/O	Description	Remark
1	VCC	I	Module Power Supply	Voltage range: 3.0V~5.0V
2	GND	G	Ground	
3	TXD	O	UART Serial Data output	
4	RXD	I	UART Serial Data input	

2.2 Mechanical Dimensions

This chapter describes the mechanical dimensions of the GGM-4538-GKBD Gmouse. Size unit (mm) .

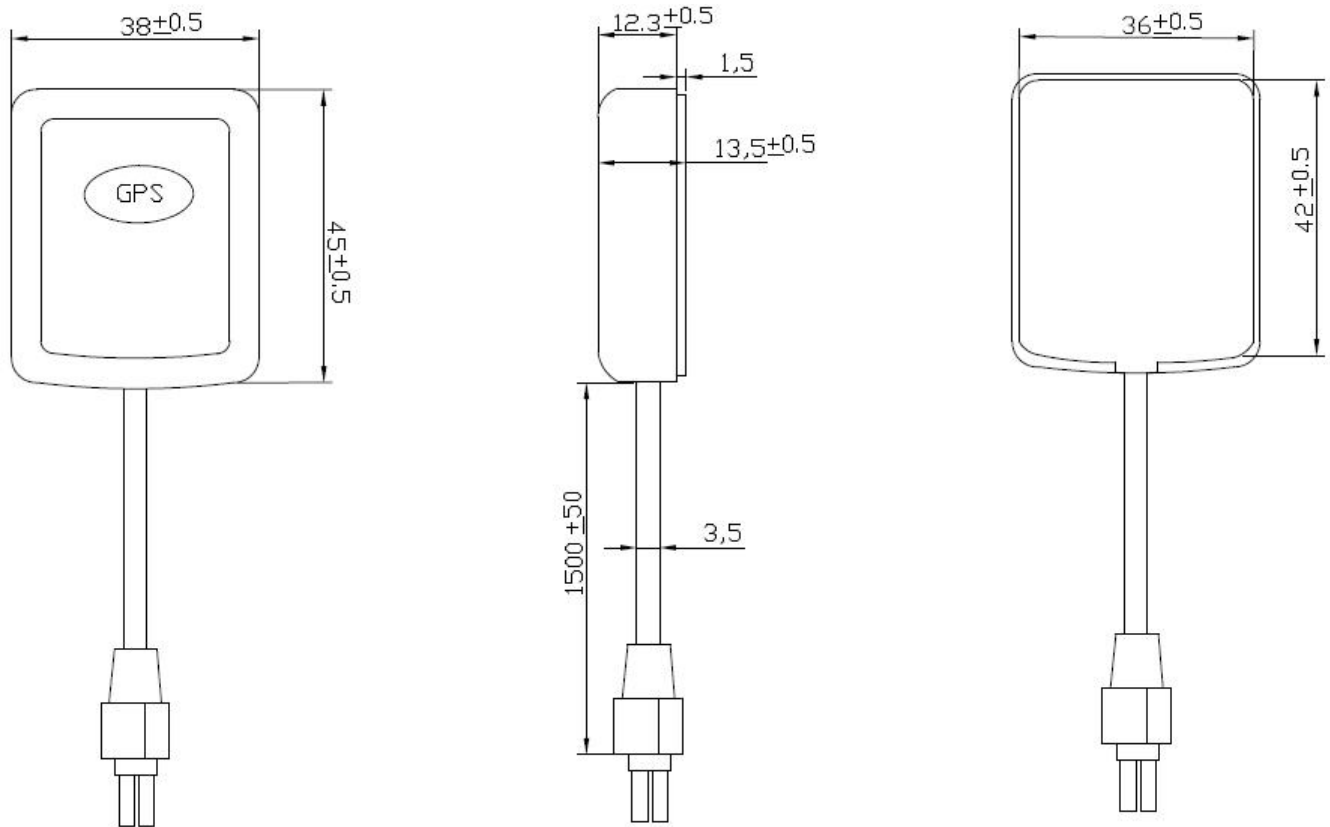


Figure 3: Specification size chart

3 NMEA 0183 Protocol

The NMEA protocol is an ASCII-based protocol, Records start with a \$ and with carriage return/line feed. GPS&Beidou specific messages all start with \$GPxxx/\$BDxxx where \$GNxxx is a three-letter identifier of the message data that follows. NMEA messages have a check sum, which allows detection of corrupted data transfers.

3.1 Location mode configuration instructions

Single system or dual system positioning mode can be selected through the configuration instructions, configuration instructions such as *Table 1*.

Table 1: Instruction configuration instructions

Pattern	Instructions	NMEA Out Put
GPS	\$PGK353,1,0,0,0,0*2A	GPRMC.GPGGA.GPGSV.GPGSA.GPGLL.GPVTG
Beidou	\$PGK353,0,0,0,0,1*2A	BDRMC.BDGGGA.BDGSV.BDGSA.BDGLL.BDVTG
GPS&Beidou	\$PGK353,1,0,0,0,1*2B	GNRMC.GNGGA.GPGSV.BDGSV.GPGSA.BDGSA.GNGLL.GNVTG

- ◇ The Gotop GGM-4538-GKBD Initialization location mode for GPS&Beidou dual mode,
Output data: \$GNRMC. \$GNGGA. \$GPGSV. \$BDGSV. \$GPGSA. \$BDGSA. \$GNGLL. \$GNVTG

3.2 NMEA-0183 data Detailed field

3.2.1 GGA-Global Positioning System Fixed Data

\$xxGGA, 161229.487,3723.2475,N, 12158.3416,W, 1,07,1.0,9.0,M.0000*18

Table 2: GGA Data Format

Name	Example	Units	Description
Message ID	\$xxGGA		GGA protocol header
UTC Position	161229.487		hhmmss.sss
Latitude	3723.2457		ddmm.mmmm
N/S indicator	N		N=north or S=south
Longitude	12158.3416		dddmm.mmmm
E/W Indicator	W		E=east or W=west
Position Fix Indicator	1		See Table 2-1
Satellites Used	07		Range 0 to 12
HDOP	1.0		Horizontal Dilution of Precision
MSL Altitude	9.0	meters	
Units	M	meters	

Geoids Separation		meters	
Units	M	meters	
Age of Diff.Corr.		second	Null fields when DGPS is not Used
Diff.Ref.Station ID	0000		
Check sum	*18		
<CR> <LF>			End of message termination

Table 2-1: Position Fix Indicators

Value	Description
0	Fix not available or invalid
1	GPS&Beidou SPS Mode, fix valid
2	Differential GPS&Beidou, SPS Mode, fix valid
3	GPS&Beidou PPS Mode, fix valid

3.2.2 GLL-Geographic Position - Latitude/Longitude

\$xxGLL , 3723.2475, N,12158.3416, W,161229.487, A*2C.

Table 3: GLL Data Format

Name	Example	Units	Description
Message ID	\$xxGLL		GLL protocol header
Latitude	3723.2475		ddmm.mmmm
N/S Indicator	N		N=north or S=south
Longitude	12158.3416		dddmm.mmmm
E/W Indicator	W		E=east or W=west
UTC Position	161229.487		hhmmss.sss
Status	A		A=data valid or V=data not valid
Check sum	*2C		
<CR> <LF>			End of message termination

3.2.3 GSA-GNSS DOP and Active Satellites

\$xxGSA , A, 3, 07, 02, 26,27, 09, 04,15, , , , , 1.8,1.0,1.5*33.

Table 4: GSA Data Format

Name	Example	Units	Description
Message	\$xxGSA		GSA protocol header
Mode 1	A		See Table 4-2

Mode 2	3		See Table 4-1
Satellite Used	07		Sv on Channel 1
Satellite Used	02		Sv on Channel 2
...
Satellite Used			Sv on Channel 66
PDOP	1.8		Position Dilution of Precision
HDOP	1.0		Horizontal Dilution of Precision
VDOP	1.5		Vertical Dilution of Precision
Check sum	*33		
<CR> <LF>			End of message termination

Table 4-1: Mode 1

Value	Description
1	Fix not available
2	2D
3	3D

Table 4-2: Mode 2

Value	Description
M	Manual-forced to operate in 2D or 3D mode
A	Automatic-allowed to automatically switch 2D/3D

3.2.4 GSV-GNSS Satellites in View

\$xxGSV , 2, 1, 07, 07, 79,048, 42, 02, 51,062, 43, 26, 36,256, 42, 27, 27, 138,42*71

\$xxGSV , 2, 2, 07, 09, 23,313, 42, 04, 19, 159, 41, 15,12,041, 42*41.

Table 5: GSV Data Format

Name	Example	Units	Description
Message ID	\$xxGSV		GSV protocol header
Number of Message	2		Range 1 to 3
Message Number	1		Range 1 to 3
Satellites in View	07		
Satellite ID	07		Channel 1(Range 1 to 66)
Elevation	79	degrees	Channel 1(Maximum 90)
Azinmuth	048	degrees	Channel 1(True, Range 0 to 359)
SNR(C/NO)	42	dBHz	Range 0 to 99,null when not tracking
...			...

Satellite ID	27		Channel 4(Range 1 to 66)
Elevation	27	degrees	Channel 4(Maximum 90)
Azimuth	138	degrees	Channel 4(True, Range 0 to 359)
SNR(C/NO)	42	dBHz	Range 0 to 99, null when not tracking
Check sum	*71		
<CR> <LF>			End of message termination

✧ Depending on the number of satellites tracked multiple messages of GSV data may be required.

3.2.5 RMC-Recommended Minimum Specific GNSS Data

\$xxRMC, 161229.487, A, 3723.2475, N, 12158.3416, W, 0.13,309.62, 120598,, *10

Table 6: RMC Data Format

Name	Example	Units	Description
Message ID	\$xxRMC		RMC protocol header
UTS Position	161229.487		hhmmss.sss
Status	A		A=data valid or V=data not valid
Latitude	3723.2475		ddmm.mmmm
N/S Indicator	N		N=north or S=south
Longitude	12158.3416		dddmm.mmmm
E/W Indicator	W		E=east or W=west
Speed Over Ground	0.13	Knots	
Course Over	309.62	Degrees	True
Ground			
Date	120598		Dummy
Magnetic variation		Degrees	E=east or W=west
Check sum	*10		
<CR> <LF>			End of message termination

3.2.6 VTG-Course Over Ground and Ground Speed

\$xxVTG, 309.62, T, M, 0.13, N, 0.2, K*6E

Table 7: VTG Data Format

Name	Example	Units	Description
Message ID	\$xxVTG		VTG protocol header

Course	309.62	Degrees	Measured heading
Reference	T		True
Course		Degrees	Measured heading
Reference	M		Magnetic
Speed	0.13	Knots	Measured horizontal speed
Units	N		Knots
Speed	0.2	Km/hr	Measured horizontal speed
Units	K		Kilometer per hour
Check sum	*6E		
<CR> <LF>			End of message termination

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