

## General Description

The GOTOP GGM-4538-HD is a complete GPS engine module that features super sensitivity, ultra low power and small form factor. The GPS signal is applied to the antenna input of module, and a complete serial data message with position, velocity and time information is presented at the serial interface with NMEA protocol or custom protocol.

Its  $-163\text{dBm}$  tracking sensitivity extends positioning coverage into place like urban canyons and dense foliage environment where the GPS was not possible before. The small form factor and low power consumption make the module easy to integrate into portable device like PNDs, mobile phones, cameras and vehicle navigation systems.

### Applications

- LBS (Location Based Service)
- PND (Portable Navigation Device)
- Vehicle navigation system
- Mobile phone



**Figure : GGM-4538-HD  
Top View**

### Features

- Build on high performance, low-power CEC Huada HD8020 chipset
- Ultra high Track sensitivity:  $-163\text{dBm}$
- Extremely fast TTFF at low signal level
- Built in high gain LNA
- The built-in super capacitor for backup ephemeris
- Low power consumption: Max  $60\text{mA}@3.3\text{V}$
- NMEA-0183 compliant protocol or custom protocol
- Operating voltage:  $3.3\text{V}$  to  $5.0\text{V}$
- Operating temperature range:  $-40$  to  $85^\circ\text{C}$
- Patch Antenna Size:  $25 \times 25 \times 4\text{mm}$
- Small form factor:  $45 \times 38 \times 13\text{mm}$
- Communication type: UART/TTL
- Wire interface type: XH2.0mm spacing terminal, 4Pin, L=500cm
- RoHS compliant (Lead-free)

# 1 Description

## 1.1. Key Features

Parameter	Specification
Power Supply	<ul style="list-style-type: none"> <li>Supply voltage: 3.3V~5.0V Typical: 3.3V</li> </ul>
Power Consumption	<ul style="list-style-type: none"> <li>Acquisition: 60mA @VCC=VBAT=3.3V</li> <li>Tracking: 45mA @VCC=VBAT=3.3V</li> <li>Backup: 25uA @VBAT=3.3V</li> </ul>
Receiver Type	<ul style="list-style-type: none"> <li>Code 72 search channels</li> <li>GPS&amp;QZSS L1 1575.42MHz C/A</li> <li>SBAS: WAAS, EGNOS, MSAS, GAGAN</li> </ul>
Sensitivity	<ul style="list-style-type: none"> <li>Tracking: -163dBm</li> <li>Re-acquisition: -156dBm</li> <li>Acquisition: -146dBm</li> </ul>
TTF (Autonomous)	<ul style="list-style-type: none"> <li>Cold start: 35s typ @-130dBm</li> <li>Warm start: 30s typ @-130dBm</li> <li>Hot start: 1s typ @-130dBm</li> </ul>
Horizontal Position Accuracy (Autonomous)	<ul style="list-style-type: none"> <li>&lt;2.5m CEP @-130 dBm</li> </ul>
Update Rate	<ul style="list-style-type: none"> <li>1Hz</li> </ul>
Accuracy of 1PPS Signal	<ul style="list-style-type: none"> <li>not enabled</li> </ul>
Acceleration Accuracy	<ul style="list-style-type: none"> <li>Without aid: 0.1m/s<sup>2</sup></li> </ul>
Dynamic Performance	<ul style="list-style-type: none"> <li>Maximum altitude: 18,000m</li> <li>Maximum velocity: 515m/s</li> <li>Acceleration: 4G</li> </ul>
UART Port	<ul style="list-style-type: none"> <li>UART Port: TXD</li> <li>Supports baud rate from 4800bps to 115200bps, 9600bps by default</li> <li>UART port is used for NMEA output</li> </ul>
Temperature Range	<ul style="list-style-type: none"> <li>Normal operation: -40°C ~ +85°C</li> <li>Storage temperature: -45°C ~ +125°C</li> </ul>
Physical Characteristics	<ul style="list-style-type: none"> <li>Size: 45±0.20 × 38±0.20 × 13±0.50mm</li> <li>Connecting line specifications: XH2.0mm spacing terminal, 4Pin, L=500cm</li> <li>Weight: Approx.25g</li> </ul>

### 1.2 Power Supply

Regulated power for the GGM-4538-HD is required. The VCC Pin Need a stable DC voltage supply. Power supply ripple must be less than 30mV. The input voltage Vcc should be 3.3V~5.0V, Recommended power supply voltage is 3.3V . maximum current is 60mA. Suitable decoupling must be provided by external decoupling circuitry.

### 1.3 UART Ports

The module supports two full duplex serial channels UART. All serial connections are at 3V CMOS logic levels, if need different voltage levels, use appropriate level shifters. The baud rate of both serial ports are fully programmable, the data format is however fixed: X, N, 8, 1, i.e. X baud rate, no parity, eight data bits and one stop bit, no other data formats are supported, LSB is sent first. The modules default baud rate is set up 9600bps, however, the user can change the default baud rate to any value from 4800 bps to 115kbps. UART port can be used for firmware upgrade, NMEA output and Huada proprietary commands input.

## 2 Application

The Gmouse is equipped with a 4-pin terminal head connects to your application platform.

The GGM-4538-HD Gmouse It consists of a Huada HD8020 single chip GPS IC which includes the RF part and Baseband part, a patch antenna, a LNA, a SAW filter, a TCXO, a crystal oscillator, Also comes with a 0.22F crystal capacitor ,can backup satellite ephemeris about 2 hour.

### 2.1. Pin Assignment

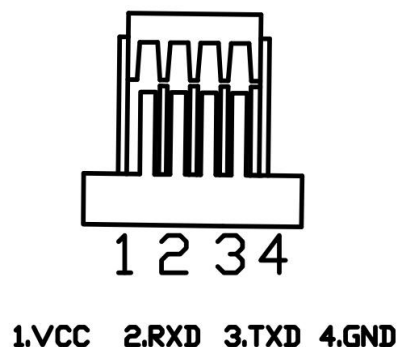


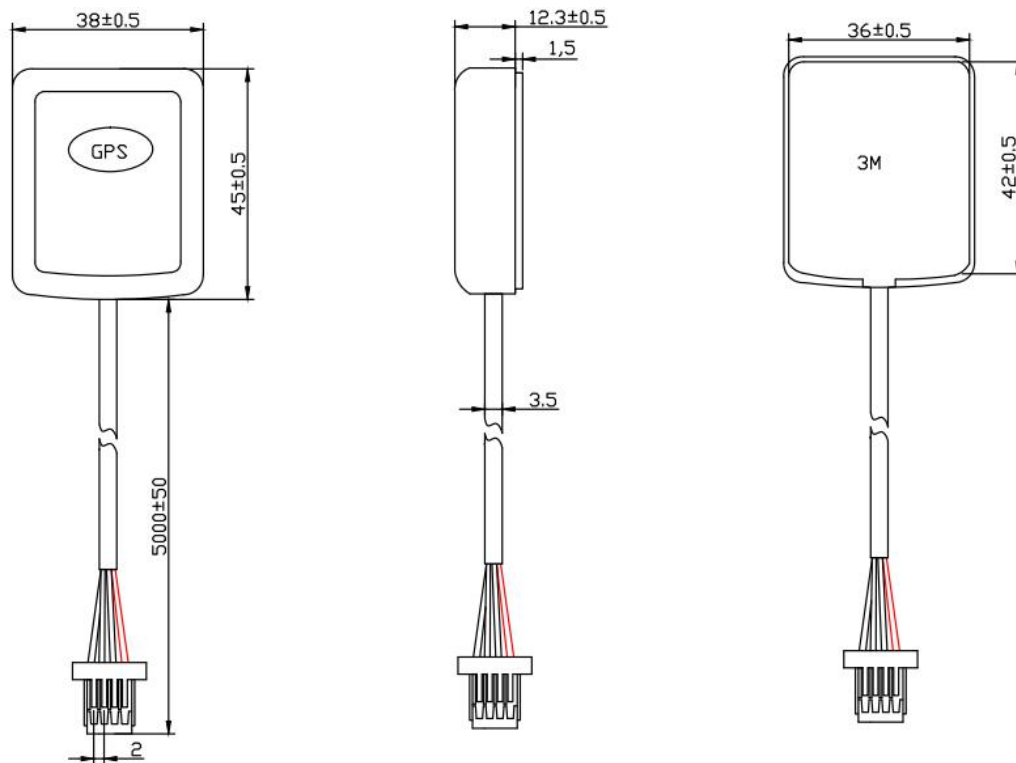
Figure 2: Pin Assignment

**CON Pin Description**

Pin No.	Pin name	I/O	Description	Remark
1	VCC	I	Module Power Supply	Voltage range: 3.3V~5.0V
2	RXD	I	UART Serial Data input	
3	TXD	O	UART Serial Data output	
4	GND	G	Ground	

**2.2 Mechanical Dimensions**

This chapter describes the mechanical dimensions of the GGM-4538-HD Gmouse. Size unit (mm) .



**Figure 3:** Specification size chart

### 3 NMEA 0183 Protocol

The NMEA protocol is an ASCII-based protocol, Records start with a \$ and with carriage return/line feed. GPS specific messages all start with \$GPxxx/\$BDxxx where \$GNxxx is a three-letter identifier of the message data that follows. NMEA messages have a check sum, which allows detection of corrupted data transfers.

The Gotop GGM-4538-HD The initial mode is GPS supports the following NMEA-0183 messages: \$GPRMC.\$GPGGA.\$GPGSV..\$GPGSA..\$GPGLL.\$GPVTG.

**Table 1: NMEA-0183 Output Messages**

NMEA Record	DESCRIPTION
GGA	Global positioning system fixed data
GLL	Geographic position—latitude/longitude
GSA	GPS DOP and active satellites
GSV	GPS satellites in view
RMC	Recommended minimum specific GPS data
VTG	Course over ground and ground speed

#### 3.1 GGA-Global Positioning System Fixed Data

\$xxGGA, 161229.487,3723.2475,N, 12158.3416,W, 1,07,1.0,9.0,M.0000\*18

**Table 2: GGA Data Format**

Name	Example	Units	Description
Message ID	\$xxGGA		GGA protocol header
UTC Position	161229.487		hhmmss.sss
Latitude	3723.2475		ddmm.mmmm
N/S indicator	N		N=north or S=south
Longitude	12158.3416		dddmm.mmmm
E/W Indicator	W		E=east or W=west
Position Fix Indicator	1		See Table 2-1
Satellites Used	07		Range 0 to 12
HDOP	1.0		Horizontal Dilution of Precision
MSL Altitude	9.0	meters	
Units	M	meters	
Geoids Separation		meters	
Units	M	meters	
Age of Diff.Corr.		second	Null fields when DGPS is not Used
Diff.Ref.Station ID	0000		

Check sum	*18		
<CR> <LF>			End of message termination

**Table 2-1: Position Fix Indicators**

Value	Description
0	Fix not available or invalid
1	GPS SPS Mode, fix valid
2	Differential GPS, SPS Mode, fix valid
3	GPS PPS Mode, fix valid

### 3.2 GLL-Geographic Position – Latitude/Longitude

\$xxGLL , 3723.2475, N,12158.3416, W,161229.487, A\*2C.

**Table 3: GLL Data Format**

Name	Example	Units	Description
Message ID	\$xxGLL		GLL protocol header
Latitude	3723.2475		ddmm.mmmm
N/S Indicator	N		N=north or S=south
Longitude	12158.3416		dddmm.mmmm
E/W Indicator	W		E=east or W=west
UTC Position	161229.487		hhmmss.sss
Status	A		A=data valid or V=data not valid
Check sum	*2C		
<CR> <LF>			End of message termination

### 3.3 GSA-GPS DOP and Active Satellites

\$xxGSA , A, 3, 07, 02, 26,27, 09, 04,15, , , , , 1.8,1.0,1.5\*33.

**Table 4: GSA Data Format**

Name	Example	Units	Description
Message	\$xxGSA		GSA protocol header
Mode 1	A		See Table 4-2
Mode 2	3		See Table 4-1
Satellite Used	07		Sv on Channel 1
Satellite Used	02		Sv on Channel 2
...	...		...
Satellite Used			Sv on Channel 66
PDOP	1.8		Position Dilution of Precision
HDOP	1.0		Horizontal Dilution of Precision

VDOP	1.5		Vertical Dilution of Precision
Check sum	*33		
<CR> <LF>			End of message termination

**Table 4-1: Mode 1**

Value	Description
1	Fix not available
2	2D
3	3D

**Table 4-2: Mode 2**

Value	Description
M	Manual-forced to operate in 2D or 3D mode
A	Automatic-allowed to automatically switch 2D/3D

### 3.4 GSV-GPS Satellites in View

\$xxGSV , 2, 1, 07, 07, 79,048, 42, 02, 51,062, 43, 26, 36,256, 42, 27, 27, 138,42\*71

\$xxGSV, 2, 2, 07, 09, 23,313, 42, 04, 19, 159, 41, 15,12,041, 42\*41.

**Table 5: GGA Data Format**

Name	Example	Units	Description
Message ID	\$xxGSV		GSV protocol header
Number of Message	2		Range 1 to 3
Message Number	1		Range 1 to 3
Satellites in View	07		
Satellite ID	07		Channel 1(Range 1 to 66)
Elevation	79	degrees	Channel 1(Maximum 90)
Azinmuth	048	degrees	Channel 1(True, Range 0 to 359)
SNR(C/NO)	42	dBHz	Range 0 to 99,null when not tracking
...			...
Satellite ID	27		Channel 4(Range 1 to 66)
Elevation	27	degrees	Channel 4(Maximum 90)
Azimuth	138	degrees	Channel 4(True, Range 0 to 359)
SNR(C/NO)	42	dBHz	Range 0 to 99, null when not tracking
Check sum	*71		
<CR> <LF>			End of message termination

Depending on the number of satellites tracked multiple messages of GSV data may be required.

### 3.5 RMC-Recommended Minimum Specific GPS Data

\$xxRMC, 161229.487, A, 3723.2475, N, 12158.3416, W, 0.13,309.62, 120598,, \*10

**Table 6: RMC Data Format**

Name	Example	Units	Description
Message ID	\$xxRMC		RMC protocol header
UTS Position	161229.487		hhmmss.sss
Status	A		A=data valid or V=data not valid
Latitude	3723.2475		ddmm.mmmm
N/S Indicator	N		N=north or S=south
Longitude	12158.3416		dddmm.mmmm
E/W Indicator	W		E=east or W=west
Speed Over Ground	0.13	Knots	
Course Over	309.62	Degrees	True
Ground			
Date	120598		Dummy
Magnetic variation		Degrees	E=east or W=west
Check sum	*10		
<CR> <LF>			End of message termination

### 3.6 VTG-Course Over Ground and Ground Speed

\$xxVTG, 309.62, T, M, 0.13, N, 0.2, K\*6E

**Table 7: VTG Data Format**

Name	Example	Units	Description
Message ID	\$xxVTG		VTG protocol header
Course	309.62	Degrees	Measured heading
Reference	T		True
Course		Degrees	Measured heading
Reference	M		Magnetic
Speed	0.13	Knots	Measured horizontal speed
Units	N		Knots
Speed	0.2	Km/hr	Measured horizontal speed
Units	K		Kilometer per hour
Check sum	*6E		
<CR> <LF>			End of message termination



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