General Description

GT-1612-HDBD is a high performance, compact and low power consumption module powered by HD8020 single chip GNSS solution with full independence intellectual property targeted for location awareness and logistic transportation markets. Its newly designed CYNOSURE II architecture is optimized to offer a seamless experience in dense urban canyons that gives the shortest time to position fix and continues to work wherever they are.

GT-1612-HDBD is designed with intelligent power control mechanism in mind, which provides the most flexible power modes and performs the best in class power consumption. The low voltage detection actives whenever main/backup battery drops below normal. Micro power backup mode eliminates the need to turn off the system power completely, while enabling the ability to communicate with external device in deep sleep mode.

Applications

- LBS (Location Based Service)
- PND (Portable Navigation Device)
- Vehicle navigation system
- Mobile phone

Figure: GT-1612-HDBD Top View

Features

- Build on high performance, low-power CEC Huada HD8020 chip set
- Ultra high Track sensitivity: -162dBm
- Extremely fast TTFF at low signal level
- Built in high gain LNA
- Low power consumption: Max 60mA@3.3V
- NMEA-0183 compliant protocol or custom protocol
- Operating voltage: 2.8V to 3.6V
- Operating temperature range:-40to85℃
- SMD type with stamp holes
- Small form factor: 16x12x2.6mm
- RoHS compliant (Lead-free)

1 Description

1.1. Key Features

Table 1: Key Features

Parameter	Specification
Power Supply	• Supply voltage: 2.8V~3.6V Typical: 3.3V
Power Consumption	• Acquisition: 60mA @VCC=V_BCKP=3.3V • Tracking: 45mA @VCC=V_BCKP=3.3V • Backup: 25uA @V_BCKP=3.3V
Receiver Type	• Code 72 search channels • GPS&QZSS L1 1575.42MHz C/A , Beidou B1 1561.098MHz SBAS: WAAS, EGNOS, MSAS, GAGAN
Sensitivity	• Tracking: -162dBm • Re-acquisition: -156dBm • Acquisition: -147dBm
TTFF	• Cold start: 35s typ @-130dBm • Warm start: 30s typ @-130dBm • Hot start: 1s typ @-130dBm
Horizontal Position Accuracy (Autonomous)	• <2.5m CEP @-130 dBm
Update Rate	• 1Hz
Accuracy of 1PPS Signal	• Typical accuracy: ±10ns • Time pulse width : 100ms
Acceleration Accuracy	• Without aid: 0.1m/s²
Dynamic Performance	• Maximum altitude: 18,000m • Maximum velocity: 515m/s • Acceleration: 4G
UART Port	• UART Port: TXD and RXD • Supports baud rate from 4800bps to 115200bps, 9600bps by default • UART port is used for NMEA output, Huada proprietary commands input
Temperature Range	• Normal operation: -40°C ~ +85°C • Storage temperature: -45°C ~ +125°C
Physical Characteristics	• Size: 16±0.15 × 12±0.15 × 2.6±0.1mm • Weight: Approx. 0.92g

1.2. Block Diagram

The following figure shows a block diagram of GT-1612-HDBD module. It consists of a single chip GNSS IC which includes the RF part and Baseband part, a LNA, a SAW filter, a TCXO, a crystal oscillator.

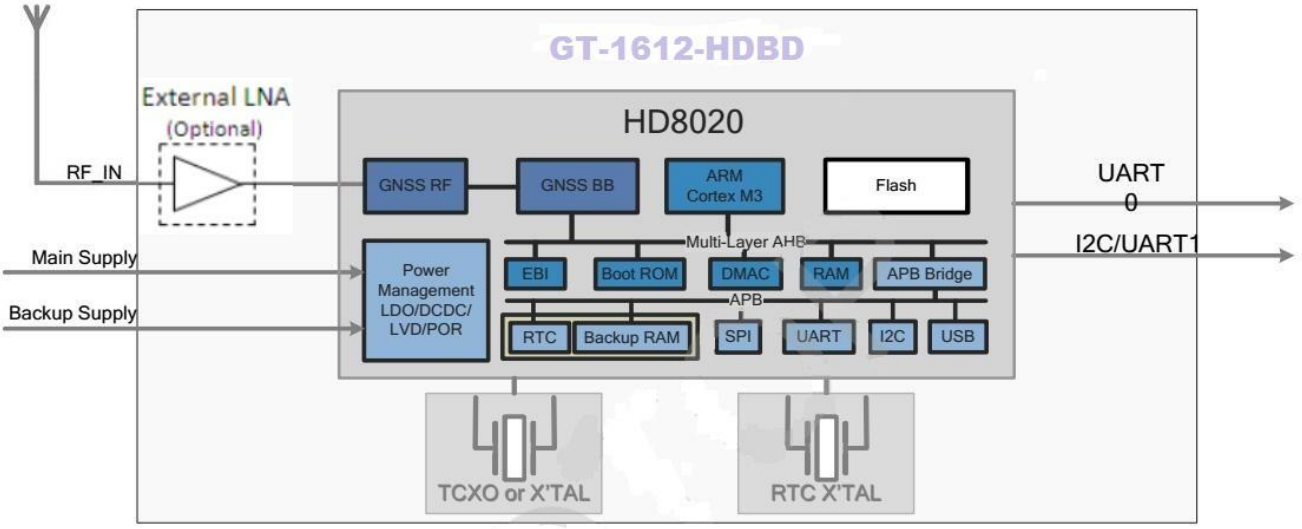


Figure 1: Block Diagram

2 Application

The module is equipped with a 18-pin SMT pad that connects to your application platform. Sub-interfaces included in the pad are described in details in the following chapters.

2.1. Pin Assignment

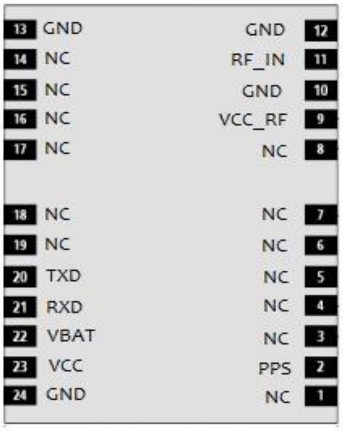


Figure 2: Pin Assignment

2.2. Pin Definition

Power Supply					
Pin Name	Pin No.	I/O	Description	DC Characteristics	Comment
VCC	23	I	Main power supply	Vmax=3.6V Vmin=2.8V Vnom=3.3V	Supply current not less than 100mA.
VBAT	22	I	Backup power supply	Vmax=3.6V Vmin=1.8V Vnom=3.3V	Supply power for RTC domain. The VBAT pin can be directly supplied power by battery or connect it to VCC.
GND	10.12. 13.24	G	Ground.		Assure a good GND connection to all GND pins of the module, preferably with a large ground plane.
UART Port					
Pin Name	Pin No.	I/O	Description	DC Characteristics	Comment
RXD	21	I	Receive data	VILmin=-0.3V VILmax=0.8V VIHmin=2.0V VIHmax=3.6V	
TXD	20	O	Transmit data	VOLmin=-0.3V VOLmax=0.4V VOHmin=2.4V VOHmax=3.1V	
RF Interface					
Pin Name	Pin No.	I/O	Description	DC Characteristics	Comment
RF_IN	11	I	External active antenna RF input		Characteristic impedance of 50Ω
VCC_RF	9	O	Active antenna power output	Vnom=3.3V	Output Voltage RF section. VCC_RF can be selected according to the type of antenna.
Other Interfaces					
Pin Name	Pin No.	I/O	Description	DC Characteristics	Comment
PPS	3	O	One pulse per second	VOLmin=-0.3V VOLmax=0.4V VOHmin=2.4V VOHmax=3.1V	Synchronized at rising edge, the pulse width is100ms. If unused, keep this pin open.

2.3. Power Supply

VCC pin supplies power for BB, RF, I/O, LNA, Antenna. The load current of VCC varies according to the VCC level, processor load, the number of tracked satellites and the rate of satellite re-acquisition. Using external active antenna will consume additional 11mA from our module. So it is important to supply sufficient current and make the power clean and stable. VCC supply ripple voltage should meet the requirement: 54mV (RMS) max @f=0…3MHz and 15mV (RMS) max@f >3MHz. You should choose the LDO without built-in output high-speed discharge function to keep long output voltage drop-down period. The decouple combination of 10uF and 100nF capacitor is recommended nearby VCC pin.

The VBAT pin supplies power for RTC domain. It should be valid when power on the module. The voltage of RTC domain ranges from 1.8V to 3.6V. In order to achieve a better TTFF, RTC domain should be valid all the time. It can supply power for SRAM memory in RTC domain which contains all the necessary GPS&Beidou information for quick start-up and a small amount of user configuration variables.

✧ The module's internal power construction is shown as below.

VCC supplies power for PMU, and VBAT supplies power for RTC domain. TIMER signal highlighted in red in the following figure belongs to RTC domain and can be used to control the power switch on/off.

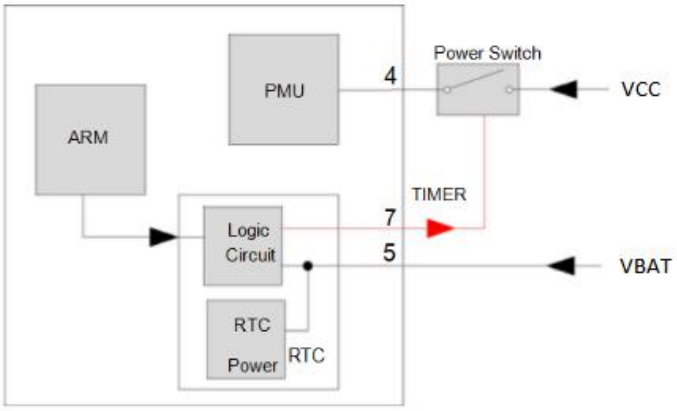


Figure 3: Internal Power Construction

✧ Power supply solutions for GT-1612-HDBD module are listed as the following.

The simplest power circuit for GT-1612-HDBD module is 3.3V power source connected to VCC pin and VBAT pin of the module directly. In this case, once you powered on the module, the full cold start will be implemented.

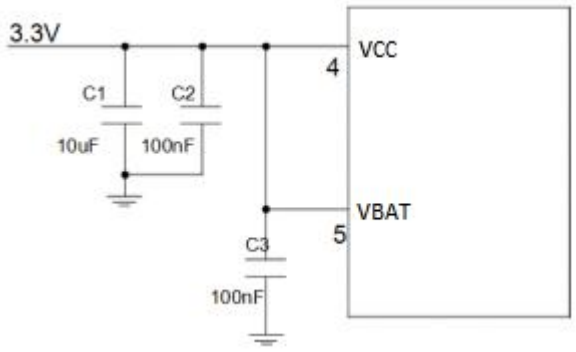


Figure 4: Reference Circuit for Power Supply

✧ If your power supply circuit adopts the design mentioned above , GT-1612-HDBD module does not support backup mode.

The other way is feeding VBAT through a backup battery directly. The module will enter into backup mode when power source (3.3V) is cut off. Furthermore,it is necessary to add an external charging circuit.for rechargeable battery. The detailed schematic (mount R2 with 0R to replace Power switch) is shown as there is no charge source when power source (3.3V) is cut off. MS621FE FL11E from Seiko is recommended. The consumption of VBAT is as low as 7uA in backup mode.

The schematic with power supply circuit is shown as below. As power source (3.3V) is always valid and the battery is charged continuously, the capacity of the battery can be small. The detailed schematic for power switch circuit is shown in ***Figure 5.***

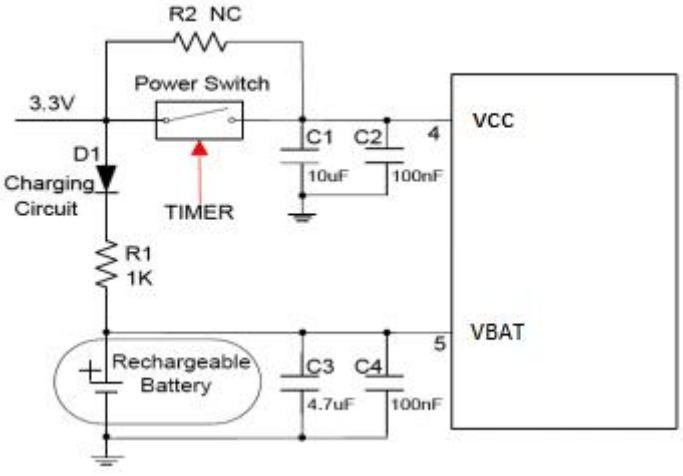


Figure 5: Reference Charging Circuit for Chargeable Battery

VCC does not supply power for RTC domain in GT-1612-HDBD module, so the VBAT pin must be powered externally. Furthermore, it is strongly recommended to supply power to VBAT through a backup battery, which can ensure GT-1612-HDBD module improves TTFF after next restart. For details about TTFF.

2.4. UART Interface

The module provides one universal asynchronous receiver& transmitter serial port. The module is designed as DCE (Data Communication Equipment), following the traditional DCE-DTE (Data Terminal Equipment) connection. The module and the client (DTE) are connected through the signals shown in the following figure. It supports data baud-rate from 4800bps to 115200bps.

UART port:

TXD: Send data to the RXD1 signal line of DTE.
RXD: Receive data from the TXD1 signal line of DTE.

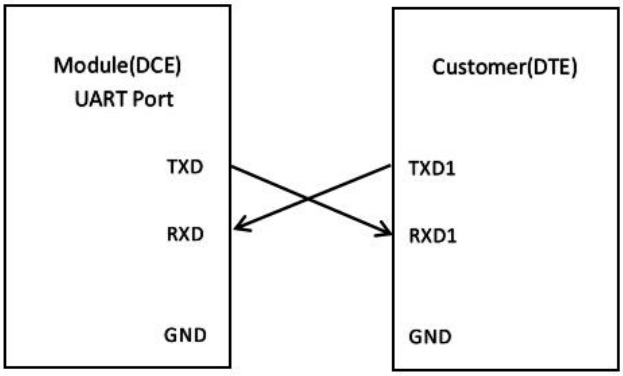


Figure 6: Connection of Serial Interfaces

This UART port has the following features:

- UART port can be used for NMEA output and proprietary commands input.
- The default output NMEA type setting is RMC, GGA, GSA, GSV, GLL, VTG
- UART port supports the following data rates:
  4800, 9600, 14400, 19200, 38400, 57600, 115200bps.
  The default setting is 9600bps, 8 bits, no parity bit, 1 stop bit.
- Hardware flow control and synchronous operation are not supported.

The UART port does not support the RS-232 level but only CMOS level. If the module's UART port is connected to the UART port of a computer, it is necessary to add a level shift circuit between the module and the computer. Please refer to the following figure.

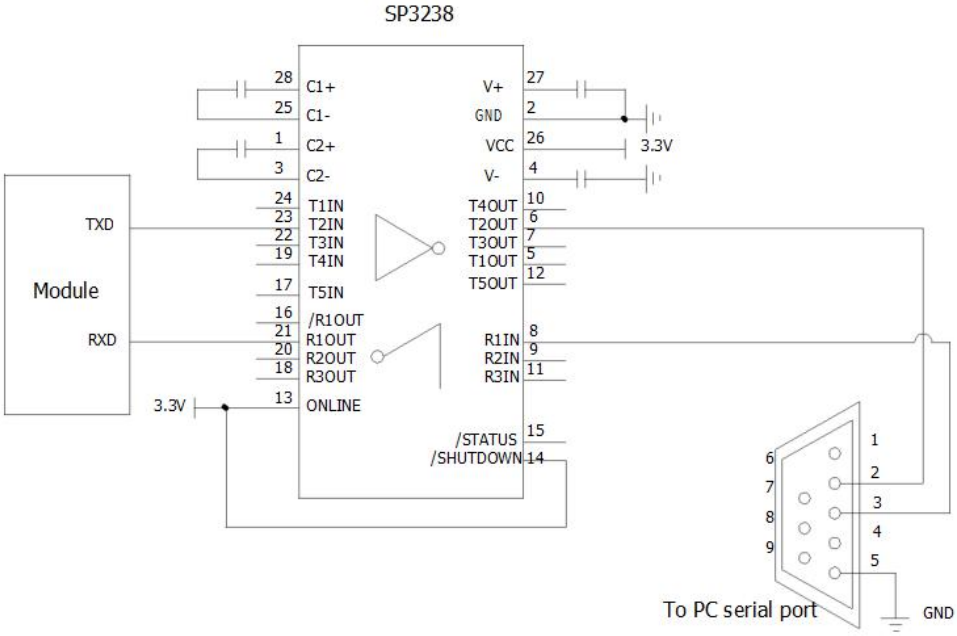


Figure 7: RS-232 Level Shift Circuit

2.5. PPS VS. NMEA

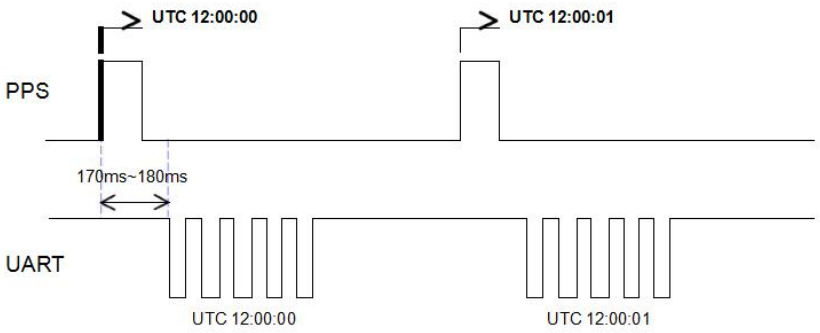


Figure 8: PPS VS. NMEA Timing

This feature only supports 1Hz NMEA output and baud rate at 14400~115200bps. At baud rate of 9600 and 4800bps, it only supports RMC NMEA sentence. Because at low baud rate, per second transmission may exceed one second if there are many NMEA sentences output.

3 Antenna Interfaces

3.1. PCB Design Guide

The GT-1612-HDBD GPS&Beidou receiver is designed for supporting the active antenna or passive antenna connected with pin RF_IN. The gain of active antenna should be no less than 15dB. The maximum noise figure should be no more than 2.5dB and output impedance is at 50 Ohm.

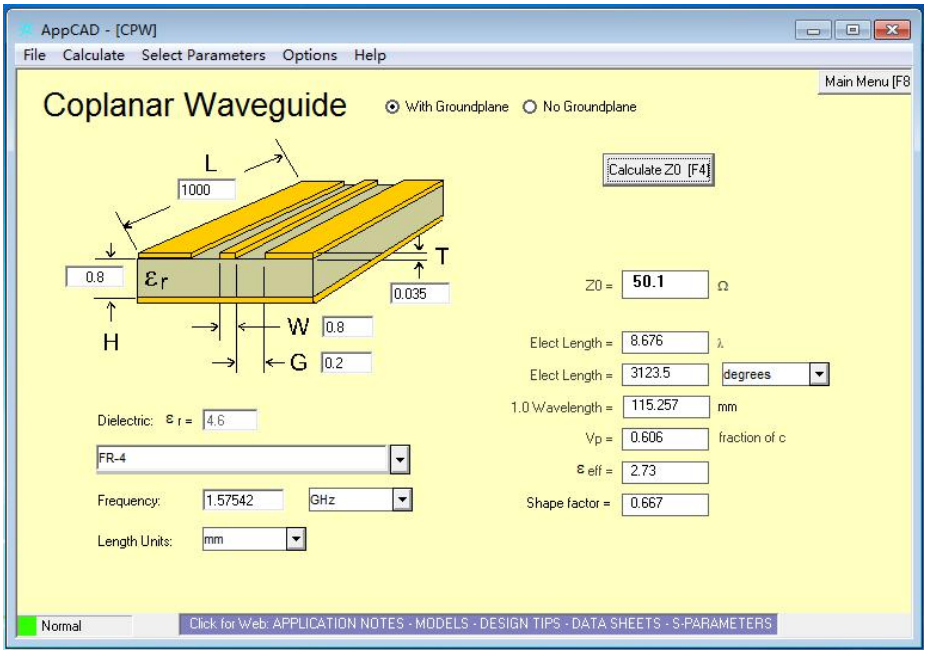


Figure 9: Antenna design requirements

3.2. External Active Antenna

The following figure is a typical reference design with active antenna. In this mode, DC on the VCC_RF pin is powered by VCC and supplies power to the external active antenna.

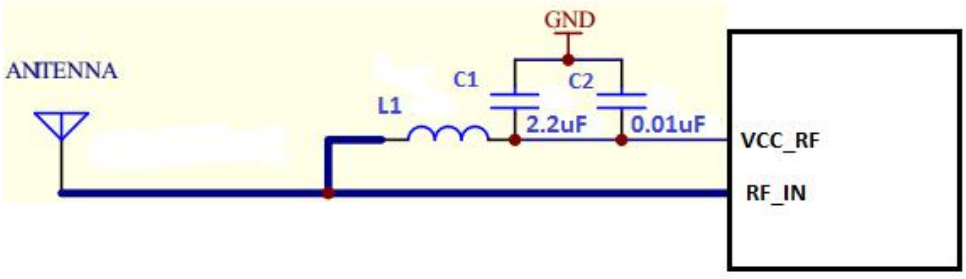


Figure 10: Reference Design for Active Antenna

C1, C2, L1 is used for power supply and filtering effect to the external active antenna, RF_IN antenna to a circuit part (BOLD line) for high frequency microstrip line, PCB in the design of this part of the line to calculate the characteristic impedance of the high-frequency line according to the principle of high frequency wiring.

✧ Requirements: this section of the line in the 1575.42MHz frequency characteristic impedance requirement is 50 ohm.

Table 2: Recommended Active Antenna Specification

Antenna Type	Specification
Active Antenna	Center frequency: 1575.42MHz Band width: >5MHZ VSWR: <2 (Typ.) Polarization: RHCP or Linear Noise figure: <1.5dB Gain (antenna): >-2dBi Gain (embedded LNA): 20dB (Typ.) Total gain: >18dBi(Typ.)

4 Electrical, Reliability and Radio Characteristics

4.1. Absolute Maximum Ratings

Absolute maximum ratings for power supply and vol age on digital pins of the module are listed in the following table.

Table 3: Absolute Maximum Ratings

values within the specified boundaries by using appropriate protection diodes.

Parameter	Min.	Max.	Unit
Power Supply Voltage (VCC)	-0.3	3.6	V
Backup Battery Voltage (VBAT)	-0.3	3.6	V
Input Voltage at Digital Pins	-0.3	3.6	V
Input Power at RF_IN		15	dBm
Storage Temperature	-45	125	°C

✧ Stressing the device beyond the “Absolute Maximum Ratings” may cause permanent damage. These are stress ratings only. The product is not protected against over voltage or reversed voltage. If necessary, voltage spikes exceeding the power supply voltage specification, given in table above, must be limited to values within the specified boundaries by using appropriate protection diodes.

4.2. Operating Conditions

Table 4: Power Supply Ratings

Parameter	Description	Conditions	Min.	Typ.	Max.	Unit
VCC	Supply voltage	Voltage must stay within the min/max values, including voltage drop, ripple, and spikes.	2.8	3.3	3.6	V
IVCCP	Peak supply current	VCC=3.3V			100	mA
VBAT	Backup voltage supply		1.8	3.3	3.6	V
TOPR	Normal operating temperature		-40	25	80	°C

✧ The figure IVCCP can be used to determine the maximum current capability of power supply.
✧ Operation beyond the "Operating Conditions" is not recommended and extended exposure beyond the "Operating Conditions" may affect the device’s reliability.

4.3. Current Consumption

The values for current consumption are shown in the following table.

Table 5: Current Consumption

Parameter	Conditions	Min.	Typ.	Max.	Unit
I_{VCC} @Acquisition	VCC=V BCKP=3.3V		60		mA
I_{VCC} @Tracking	VCC=VBAT=3.3V		45		mA
I_{VCC} @Standby	VCC=VBAT=3.3V		2.0		mA
I_{BCKP} @Backup	VBAT=3.3V		25		uA

The tracking current is tested in the following conditions:

✧ In Cold Start, 10 minutes after First Fix.
✧ In Hot Start, 15 seconds after First Fix.

4.4. Electrostatic Discharge

GT-1612-HDBD module is an ESD sensitive device. ESD protection precautions should still be emphasized. Proper ESD handling and packaging procedures must be applied throughout the processing, handling and operation of any application.

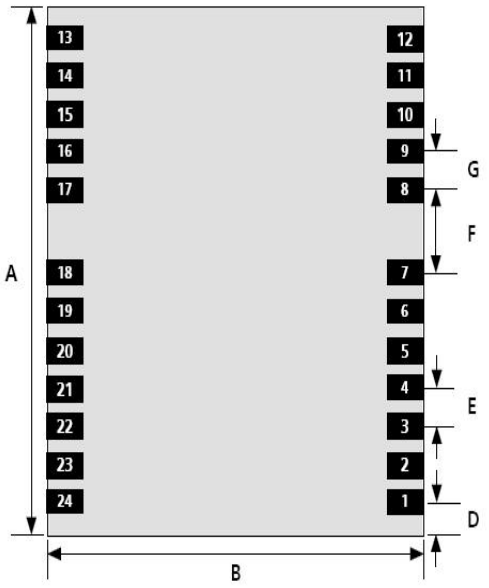
The ESD bearing capability of the module is listed in the following table. Note that you should add ESD components to module pins in particular applications.

Table 6: ESD Endurance Table (Temperature : 25°C, Humidity: 45%)

Pin	Contact Discharge	Air Discharge
RF_IN	±5KV	±10KV
VCC	±5KV	±10KV
UART	±3KV	±6KV
Others	±2KV	±4KV

5 Mechanical Dimensions

This chapter describes the mechanical dimensions of the module.



Parameter	Specification	
A	16.0 +0.6/-0.1mm	[628.8 +24/-4mil]
B	12.2 ±0.1mm	[479.5 ±4mil]
C	2.4 ±0.2mm	[94.3 ±8mil]
D	1.0 +0.3/-0.1mm	[39.3 +18/-4mil]
E	1.1 ±0.1mm	[43.2 ±4mil]
F	3.0 ±0.1mm	[117.9 ±4mil]
G	1.1 ±0.1mm	[43.2 ±4mil]
Weight	1.6 g	

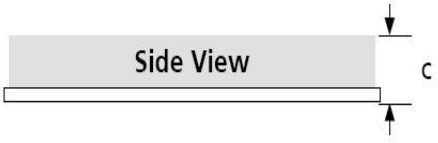


Figure 10: Bottom View Dimensions

6 Manufacturing, Packaging and Ordering Information

6.1. Assembly and Soldering

GT-1612-HDBD module is intended for SMT assembly and soldering in a Pb-free reflow process on the top side of the PCB. It is suggested that the minimum height of solder paste stencil is 100um to ensure sufficient solder volume. Pad openings of paste mask can be increased to ensure proper soldering and solder wetting over pads. It is suggested that the peak reflow temperature is 235~245° C (for SnAg3.0Cu0.5 alloy). The absolute maximum reflow temperature is 260° C. To avoid damage to the module when it is repeatedly heated, it is suggested that the module should be mounted after reflow soldering for the other side of PCB has been completed. Recommended reflow soldering thermal profile is shown below:

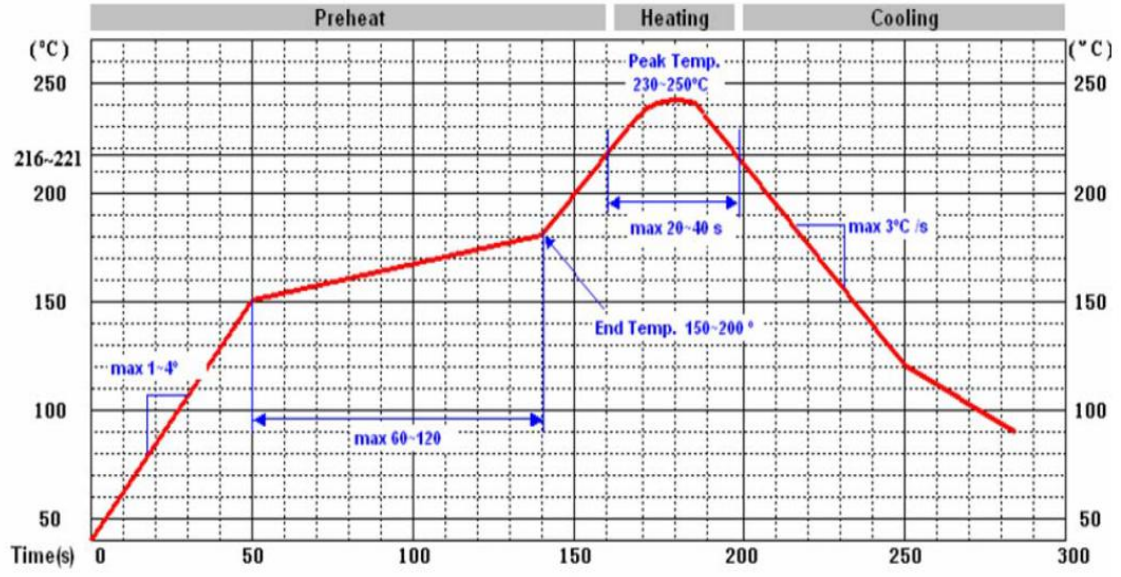


Figure 11: Recommended Reflow Soldering Thermal Profile

6.2. Moisture Sensitivity

GT-1612-HDBD module is sensitive to moisture. To prevent GT-1612-HDBD from permanent damage during reflow soldering, baking before reflow soldering is required in following cases:

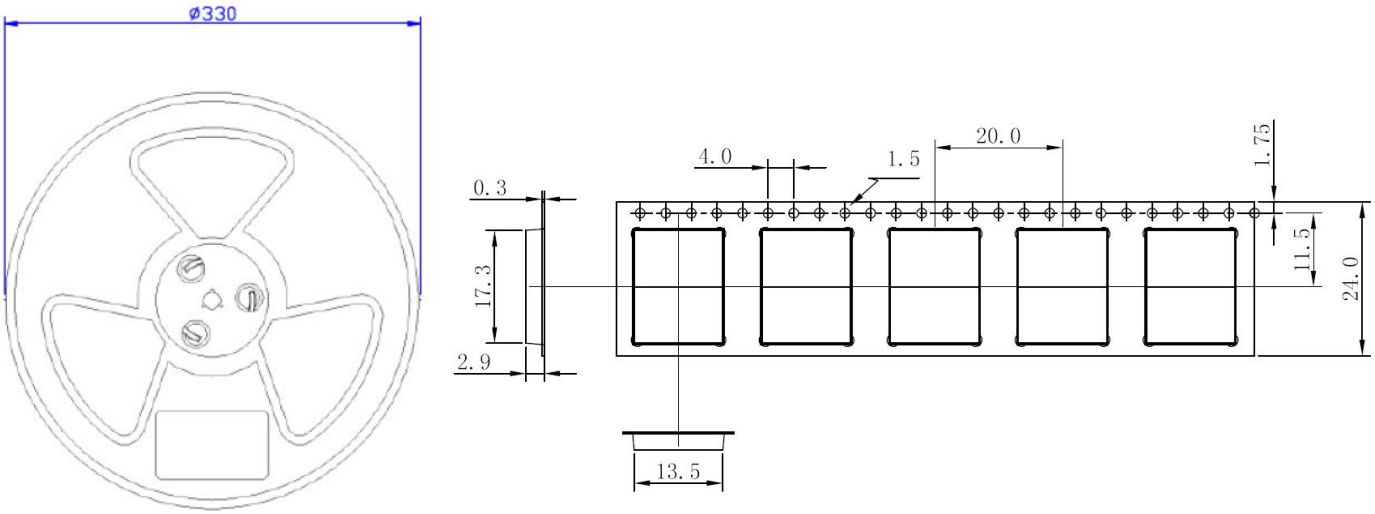
- ✧ Humidity indicator card: One or more indicating spots are no longer blue.
- ✧ The seal is opened and the module is exposed to excessive humidity.

GT-1612-HDBD should be baked for 192 hours at temperature 40°C+5°C/-0°C and <5% RH in low-temperature containers, or 24 hours at temperature 125°C±5°C in high-temperature containers. Care should be taken that the plastic tape is not heat resistant. GT-1612-HDBD should be taken out from the tape before preheating; otherwise, the tape maybe damaged by high-temperature heating.

6.3. ESD Protection

GT-1612-HDBD module is sensitive to ESD and requires special precautions when handling. Particular care must be exercised when handling patch antenna, duo to the risk of electrostatic charges.

6.4. Tape and Reel Packaging



Unit: mm
Quantity per reel: 1000pcs
Lengh per reel: 20m

Figure 12: Tape and Reel Specifications

Figure 13: Packaging physical Figure

Table 8: Reel Packaging

Model Name	MOQ for MP	Minimum Package: 1000pcs
GT-1612-HDBD	1000pcs	Size: 365mm × 350mm × 53mm N.W: 1.42kg G.W: 1.6kg

7 Appendix References

Table 9: Terms and Abbreviations

Abbreviation	Description
AGNSS	Assisted Global navigation satellite system
DGPS	Differential GPS
ESD	Electrostatic Discharge
GPS	Global Positioning System
GNSS	Global Navigation Satellite System
GGA	GNSS Fix Data
GLL	Geographic Position – Latitude/Longitude
GLONASS	Global Navigation Satellite System
GSA	GNSS DOP and Active Satellites
GSV	GNSS Satellites in View
HDOP	Horizontal Dilution of Precision
I/O	Input/Output
Kbps	Kilo Bits Per Second
LNA	Low Noise Amplifier
MSAS	Multi-Functional Satellite Augmentation System
MOQ	Minimum Order Quantity
NMEA	National Marine Electronics Association
PDOP	Position Dilution of Precision
PPS	Pulse Per Second
PRN	Pseudo Random Noise Code
QZSS	Quasi-Zenith Satellite System
RHCP	Right Hand Circular Polarization
RMC	Recommended Minimum Specific GNSS Data
SBAS	Satellite-based Augmentation System
SAW	Surface Acoustic Wave
SPDT	Single-Pole Double-Throw
TTFF	Time To First Fix

UART	Universal Asynchronous Receiver & Transmitter
VDOP	Vertical Dilution of Precision
VTG	Course over Ground and Ground Speed, Horizontal Course and Horizontal Velocity
WAAS	Wide Area Augmentation System
Inom	Nominal Current
Imax	Maximum Load Current
Vmax	Maximum Voltage Value
Vnom	Nominal Voltage Value
Vmin	Minimum Voltage Value
VIHmax	Maximum Input High Level Voltage Value
VIHmin	Minimum Input High Level Voltage Value
VILmax	Maximum Input Low Level Voltage Value
VILmin	Minimum Input Low Level Voltage Value
VImax	Absolute Maximum Input Vol age Value
VImin	Absolute Minimum Input Vol age Value
VOHmax	Maximum Output High Level Vol age Value
VOHmin	Minimum Output High Level Voltage Value
VOLmax	Maximum Output Low Level Voltage Value
VOLmin	Minimum Output Low Level Voltage Value

8. Configuration instruction Explain

The module supports the commonly used commands in configuration, The following table describes some of the parameters of the UART port configuration command,The Module power up initialization requires 300ms,Please send the sixteen system from CPU via serial port.

Table 10: Common instruction

Common commands	Instructions
Cold star	F1 D9 06 40 01 00 01 48 22
Warm start	F1 D9 06 40 01 00 02 49 23
Hot start	F1 D9 06 40 01 00 03 4A 24
Reset	F1 D9 06 40 01 00 00 47 21
GPS Stop	F1 D9 06 40 01 00 11 58 32
GPS Start	F1 D9 06 40 01 00 11 58 32
Baud rate is 4800bps	F1 D9 06 00 08 00 00 00 00 00 C0 12 00 00 E0 CE
Baud rate is 9600bps	F1 D9 06 00 08 00 00 01 0E 33 80 25 00 00 F5 61
Baud rate is 19200bps	F1 D9 06 00 08 00 00 00 00 00 00 4B 00 00 59 79
Baud rate is 38400bps	F1 D9 06 00 08 00 00 00 00 00 00 96 00 00 A4 5A
Baud rate is 57600bps	F1 D9 06 00 08 00 00 00 00 00 00 E1 00 00 EF 3B
Baud rate is 115200bps	F1 D9 06 00 08 00 00 00 00 00 00 C2 01 00 D1 E0

9 NMEA 0183 Protocol

The NMEA protocol is an ASCII-based protocol, Records start with a $ and with carriage return/line feed. GPS&Beidou specific messages all start with $GPxxx/$BDxxx where $GNxxx is a three-letter identifier of the message data that follows. NMEA messages have a check sum, which allows detection of corrupted data transfers.

This module supports three modes of instruction configuration, each mode corresponding to the NMEA data such as ***Table 11.***

Table 11: Each mode corresponds to the NMEA data

Pattern	Instructions	NMEA Out Put
GPS	F1 D9 06 0C 04 00 21 00 00 00 37 20	GPRMC.GPGGA.GPGSV.GPGSA.GPGLL.GPVTG
Beidou	F1 D9 06 0C 04 00 24 00 00 00 3A 2C	BDRMC.BDGGA.BDGSV.BDGSA.BDGLL.BDVTG
GPS& Beidou	F1 D9 06 0C 04 00 25 00 00 00 3B 30	GNRMC.GNGGA.GPGSV.BDGSV.GPGSA.BDGSA. GNGLL.GNVTG

✧ The Gotop GT-1612-HDBD Initialization location mode for GPS&Beidou dual mode,
Output data：$GNRMC.$GNGGA.$GPGSV.$BDGSV.$GPGSA.$BDGSA.$GNGLL.$GNVTG.

9.1 GGA-Global Positioning System Fixed Data

$xxGGA, 161229.487,3723.2475,N, 12158.3416,W, 1,07,1.0,9.0,M.0000*18

Table 12: GGA Data Format

Name	Example	Units	Description
Message ID	$xxGGA		GGA protocol header
UTC Position	161229.487		hhmmss.sss
Latitude	3723.2457		ddmm.mmmm
N/S indicator	N		N=north or S=south
Longitude	12158.3416		dddmm.mmmm
E/W Indicator	W		E=east or W=west
Position Fix Indicator	1		See Table 12-1
Satellites Used	07		Range 0 to 12
HDOP	1.0		Horizontal Dilution of Precision
MSL Altitude	9.0	meters	
Units	M	meters	
Geoids Separation		meters	
Units	M	meters	
Age of Diff.Corr.		second	Null fields when DGPS is not Used
Diff.Ref.Station ID	0000		
Check sum	*18		
<CR> <LF>			End of message termination

Table 12-1: Position Fix Indicators

Value	Description
0	Fix not available or invalid
1	GPS &BDSPS Mode, fix valid
2	Differential GPS, SPS Mode, fix valid
3	GPS&BD PPS Mode, fix valid

9.2 GLL-Geographic Position – Latitude/Longitude

$xxGLL , 3723.2475, N,12158.3416, W,161229.487, A*2C.

Table 13: GLL Data Format

Name	Example	Units	Description
Message ID	$xxGLL		GLL protocol header
Latitude	3723.2475		ddmm.mmmm
N/S Indicator	N		N=north or S=south
Longitude	12158.3416		dddmm.mmmm
E/W Indicator	W		E=east or W=west
UTC Position	161229.487		hhmmss.sss
Status	A		A=data valid or V=data not valid
Check sum	*2C		
<CR> <LF>			End of message temination

9.3 GSA-GNSS DOP and Active Satellites

$xxGSA , A, 3, 07, 02, 26,27, 09, 04,15, , , , , , 1.8,1.0,1.5*33.

Table 14: GSA Data Format

Name	Example	Units	Description
Message	$xxGSA		GSA protocol header
Mode 1	A		See Table 14-2
Mode 2	3		See Table 14-1
Satellite Used	07		Sv on Channel 1
Satellite Used	02		Sv on Channel 2
…	…		…
Satellite Used			Sv on Channel 66
PDOP	1.8		Position Dilution of Precision
HDOP	1.0		Horizontal Dilution of Precision
VDOP	1.5		Vertical Dilution of Precision
Check sum	*33		
<CR> <LF>			End of message termination

Table 14-1: Mode 1

Value	Description
1	Fix not available
2	2D
3	3D

Table 14-2: Mode 2

Value	Description
M	Manual-forced to operate in 2D or 3D mode
A	Automatic-allowed to automatically switch 2D/3D

9.4 GSV-GNSS Satellites in View

$xxGSV , 2, 1, 07, 07, 79,048, 42, 02, 51,062, 43, 26, 36,256, 42, 27, 27, 138,42*71
$xxGSV, 2, 2, 07, 09, 23,313, 42, 04, 19, 159, 41, 15,12,041, 42*41.

Table 15: GGA Data Format

Name	Example	Units	Description
Message ID	$xxGSV		GSV protocol header
Number of Message	2		Range 1 to 3
Message Number	1		Range 1 to 3
Satellites in View	07		
Satellite ID	07		Channel 1(Range 1 to 66)
Elevation	79	degrees	Channel 1(Maximum 90)
Azinmuth	048	degrees	Channel 1(True, Range 0 to 359)
SNR(C/NO)	42	dBHz	Range 0 to 99,null when not tracking
…			…
Satellite ID	27		Channel 4(Range 1 to 66)
Elevation	27	degrees	Channel 4(Maximum 90)
Azimuth	138	degrees	Channel 4(True, Range 0 to 359)
SNR(C/NO)	42	dBHz	Range 0 to 99, null when not tracking
Check sum	*71		
<CR> <LF>			End of message termination

Depending on the number of satellites tracked multiple messages of GSV data may be required.

9.5 RMC-Recommended Minimum Specific GNSS Data

$xxRMC, 161229.487, A, 3723.2475, N, 12158.3416, W, 0.13,309.62, 120598,, *10

Table 16: RMC Data Format

Name	Example	Units	Description
Message ID	$xxRMC		RMC protocol header
UTS Position	161229.487		hhmmss.sss
Status	A		A=data valid or V=data not valid
Latitude	3723.2475		ddmm.mmmm
N/S Indicator	N		N=north or S=south
Longitude	12158.3416		dddmm.mmmm
E/W Indicator	W		E=east or W=west
Speed Over Ground	0.13	Knots	

Course Over	309.62	Degrees	True
Ground			
Date	120598		Dummy
Magnetic variation		Degrees	E=east or W=west
Check sum	*10		
<CR> <LF>			End of message termination

9.6 VTG-Course Over Ground and Ground Speed

$xxVTG, 309.62, T, M, 0.13, N, 0.2, K*6E

Table 17: VTG Data Format

Name	Example	Units	Description
Message ID	$xxVTG		VTG protocol header
Course	309.62	Degrees	Measured heading
Reference	T		True
Course		Degrees	Measured heading
Reference	M		Magnetic
Speed	0.13	Knots	Measured horizontal speed
Units	N		Knots
Speed	0.2	Km/hr	Measured horizontal speed
Units	K		Kilometer per hour
Check sum	*6E		
<CR> <LF>			End of message termination

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